# **Probabilistic Relational Agent-Based Models**



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### 1. Motivation

- What
  - Accelerate modeling of all kinds
  - Target language for semi-automated construction of probabilistic relational agent-based models (PRAMs)
- How
  - By combining agent-based models with probability theory
  - Effectively arriving at a mass redistribution system

## 2. Elements of a PRAM

- Entities
  - Groups
    - Mass (e.g., 500 agents)
    - Attributes (e.g., age, sex, flu)
- Relations (e.g., school, hospital)
  Sites

  Locations agents can be @

  Rules

  Animate mass redistribution



#### 4. Semi-Automated Construction

- Static and dynamic rule analysis
  - Identify essential group attributes and relations
- Automatic population generation from rel. databases

### 5. Examples of Supported Rules/Models

- Fundamental stochastic processes
  - Poisson point process
- Probabilistic
  - Finite state-space time-(in)variant Markov chain
- Epidemiological
- SIS, SIR, SIRS
- Segregation model

## 6. On-Going Efforts

## **3. Modeling Levels**

- Domain Invoke domain-specific models (e.g., SIRS)
- Class Invoke a class of processes or models (e.g., MC)
- Rule Write rules directly
- Example: The SIRS model



- $\beta$  transmission rate
- $\gamma$  recovery rate
- $\alpha$  immunity loss rate ( $\alpha$  = 0 implies life-long immunity)

## 3.1. Domain Level (example in Python)

SIRSModel('flu',  $\beta=0.05$ ,  $\gamma=0.50$ ,  $\alpha=0.10$ )

**3.2. Class Level (example in Python)** 

 $\beta$ ,  $\gamma$ ,  $\alpha = 0.05$ , 0.50, 0.10

- Theoretical work on the equivalence between PRAMs and other model types
- Investigating the relationship between PRAMs and dynamical systems specified via ordinary differential equations
- Accounting for continuous group features and continuous-time simulations
- Extending the definition of population
- Allowing changes to the total population mass
- Ensuring proper amalgamation of different models within the same simulation
- Investigating the pedagogical value of PRAMs



Simulation results based on a synthetic population of ~200,000 Allegheny County students School with 88% of Low-Income Students



```
transition_matrix = {
    's': [1 - β, β, 0.00],
    'i': [ 0.00, 1 - γ, γ],
    'r': [ α, 0.00, 1 - α]
}
TimeInvMarkovChain('flu', transition_matrix)
```

3.3. Rule Level (more elaborate example in pseudo-code)

```
rule_flu_progression():
   if group.feature.flu == 's':
       p_inf = n@_{feature.flu == 'i'} / n@ # n@ - count at the group's location
       dm p_inf -> F:flu = 'i', F:mood = 'annoyed'
       nc 1 - p_inf
   if group.feature.flu == 'i':
       dm 0.2 -> F:flu = 'r', F:mood = 'happy'
       dm 0.5 -> F:flu = 'i', F:mood = 'bored'
       dm 0.3 -> F:flu = 'i', F:mood = 'annoyed'
   if group.feature.flu == 'r':
       dm 0.1 -> F:flu = 's'  # dm - distribute mass
       nc 0.9
                   # nc - no change
rule_flu_location():
   if group.feature.flu == 'i':
       if group.feature.income == '1':
           dm 0.1 -> R:@ = group.rel.home
           nc 0.9
       if group.feature.income == 'm':
           dm \ 0.6 \rightarrow R: @ = group.rel.home # R: @ - location the group is at
           nc 0.4
```

if group.feature.flu == 'r':
 dm 0.8 -> R:@ = group.rel.school
 nc 0.2

#### **3.4. Rule Level (ODEs support in development; Python)**

 $\alpha = 1.1 # baboon$   $\beta = 0.4$   $\delta = 0.1 # cheetah$  $\gamma = 0.4$ 

```
def f_lotka_volterra(t, state):
    x,y = state
    return [x * (\alpha - \beta*y), -y * (\gamma - \delta*x)]
```

r = ODESystem(f\_lotka\_volterra, ['x', 'y'], dt=0.1)

Simulation().add([r, Group(n=1, attr={'x':10, 'y':10})]).run(1000)) # initial (10,10)

h = r.get\_hist() # time series of computed values
plt.plot(h[0], h[1][0], 'b-', h[0], h[1][1], 'r-') # red-predator; blue-pray

sp_id	integer	200169				
school_id	integer	350		school 0.67	school	
income_value	integer	2125				
income	text	2	✓ income 1.0			
age	integer	16				
sex	text	2				
race	integer	8				
<b>Probes</b>						
<ul><li>Probes</li><li>Simulation</li></ul>						
Probes     Simulation     CONTROL	RUI	_ES	POPULATI PR	OBES SETTINGS		
Probes Simulation CONTROL Gents: 200169 Groups: 696 Hites: 351 RESET THE PO	RUL	-ES	POPULATI PR	OBES SETTINGS		